

Encoders

optical Encoder, digital outputs
2 channels, 120 lines per revolution

For combination with
Stepper Motors

Series PE22 – 120

		PE22 – 120	
Lines per revolution	N	120	
Frequency range ¹⁾	f	up to 30	kHz
Signal output, square wave		2	channels
Supply voltage	U _{DD}	4,5 ... 5,5	V DC
Current consumption, typical ²⁾	I _{DD}	20	mA
Pulse width	P ₀	180 ± 45	°e
Phase shift, channel A to B	Φ	90 ± 45	°e
Logic state width	S	90 ± 45	°e
Cycle	C	360 ± 30	°e
Signal rise/fall time, typical	tr/tf	0,5 / 0,1	µs
Inertia of code disc	J	0,24	gcm ²
Operating temperature range		- 20 ... + 85	°C

¹⁾ speed (rpm) = f (Hz) x 60/N
²⁾ U_{DD} = 5V: with unloaded outputs

For combination with motor

Dimensional drawing A	<L1 [mm]		
AM2224	37,80		
AM2224-R3	41,00		

Features

These incremental shaft encoders in combination with two phases stepper motors are designed for indication and control of both, shaft velocity and direction of rotation as well as for position verification.

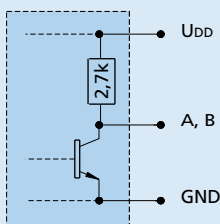
Details for the stepper motors and suitable reduction gearheads are on the corresponding data sheets.

The encoder is integrated in the Stepper Motors and extends the overall length by only 11 mm.

The supply voltage for the encoder and the stepper motors as well as the two channel output signals are interfaced through a ribbon cable with connector.

Circuit diagram / Output signals

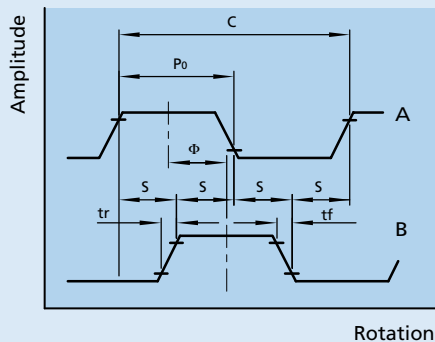
Output circuit



Recommendation:
Please use a latch to capture the outputs.

Output signals

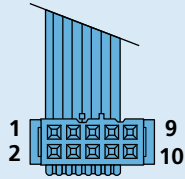
with clockwise rotation as seen from the shaft end



Connector information / Variants

No.	Function
1	Motor Phase A +
2	Motor Phase A -
3	Motor Phase B +
4	Motor Phase B -
5	U _{DD ENC}
6	GND
7	Channel A
8	Channel B
9	N.C.
10	N.C.

Connection Encoder and Motor



Connector
Serie 71600-010LF
PVC-ribbon cable

Full product description

- Example:
AM2224-AV-18-16 PE22-120
AM2224-R3-V-12-75-86 PE22-120

Dimensional drawing A

